CLAIM AMENDMENTS

Claims 1-11 (Cancelled).

1 ~~12~~. (New) An apparatus for cutting fish and fish fillets into slices comprising;

a cutting unit for cutting the fish/fillets into slices made relative to a horizontal plane;

a feeding unit having means for feeding the fish/fillets to the cutting unit, means for collecting and processing data on the fish/fillets having means for registering a length of the fish/fillet relative to a feeding direction and/or a weight of the fish/fillet, the feeding unit having an adjustable plane on which the fish/fillet is placed and fed forward, means for ~~automatically~~ automatically adjusting and setting an angle of the plane, relative to the horizontal plane, responsive to the collecting and data processing means, continuously during cutting, the angle set as a function of the length and/or the weight of the fish/fillet for cutting the fish/fillet into a plurality of slices having an equal length for a given thickness, the apparatus having gripping means for removing each cut slice from the cutting area.

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2 ~~13~~. (New) The apparatus according to claim 1 ~~12~~, wherein a sensor unit is placed at a distance relative to the cutting unit and opposite to the feeding direction for registering a beginning and an end of each fish/fillet.

3 ~~14~~. (New) The apparatus of claim 2 ~~13~~ wherein the sensor unit is a photocell.

4 ~~15~~. (New) The apparatus according to claim 1 ~~12~~, wherein the gripping means comprise at least one jaw connected in a pivotal manner around an axis.

5 ~~16~~. (New) The apparatus according to claim ~~12~~ 1, wherein the gripping means comprise at least one jaw part which is displaceable in a linear manner.

6 ~~17~~. (New) The apparatus according to claim ~~12~~ 1, further comprising securing elements for securing the fish/fillet during cutting.

7 ~~18~~. (New) The apparatus according to claim ~~16~~ 6, wherein the securing elements are wheels/drums having a periphery in which barbs are mounted which engage and secure the fish/fillet.

8 ~~19~~. (New) The apparatus according to claim ~~12~~ 1, wherein the automatic angle adjustment means comprise a microprocessor.

9 ~~20~~. (New) The apparatus according to claim ~~12~~ 1, wherein the means for setting the angle of the plane comprise a motor and a spindle to which the plane is mounted.

10 ~~21~~. (New) A method of cutting fish and fillets into slices made relative to a horizontal plane comprising;

placing a fish/fillet on a feeding unit and conveying the fish/fillet to a cutting area;

feeding the fish/fillet onto an angle adjustable conveyor in the cutting area;

setting the angle adjustable conveyor at a given angle in relation to the horizontal plane, continuously adjusting the angle relative to each slice to provide each slice with a uniform length for a given thickness and continuously adjusting the angle during cutting of an individual slice;

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feeding the fish/fillet a given first distance until a sensor is activated;

activating the cutting unit for horizontally cutting the slice;

removing the slice from the cutting area, then, repeating the feeding, adjusting and cutting steps for each cut made thereafter to provide a plurality of slices of uniform length for a given thickness.

11 ~~22~~. (New) The method according to claim 10 ~~21~~, further comprising using a gripping device to remove the slice from the cutting area, using a combined linear and rotating movement of the gripping device from a start position to an end position.

12 ~~23~~. (New) The method according to claim 11 ~~22~~, further comprising, from the end position, returning the gripping device to the start position while moving the fish/fillet forward the given first distance.

13 ~~24~~ ~~23~~. (New) The method according to claim 10 21 ~~20~~, further comprising placing the plurality of slices into packaging, moving the packaging for a given second distance synchronously while moving the fish/fillet for the given first distance.

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